

A separation method for two-row cuts

Laurent Poirrier

Joint work with Quentin Louveaux

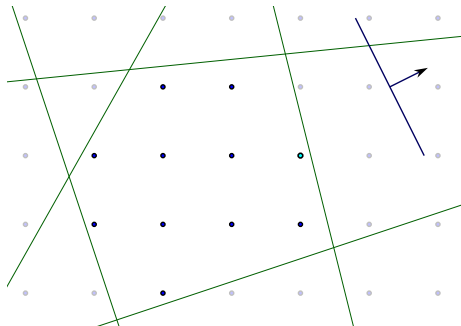
Montefiore Institute, ULg

Thursday, April 7th, 2011

Background

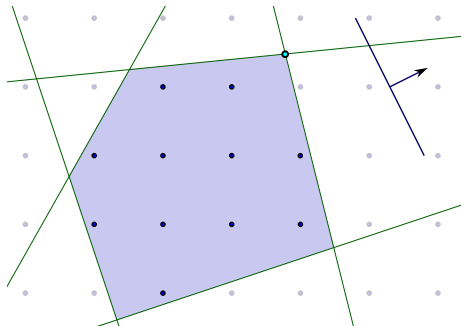
The mixed integer linear problem

$$\begin{array}{ll} \text{(MIP)} & \min \quad c^T x \\ & \text{s.t.} \quad Ax \geq b \\ & \quad \quad x_j \in \mathbb{Z}, \text{ for } j \in J \end{array}$$



The linear relaxation

$$\begin{array}{ll} \min & c^T x \\ \text{s.t.} & Ax \geq b \\ & \text{--- } x_j \in \mathbb{Z}, \text{ for } j \in J \end{array}$$



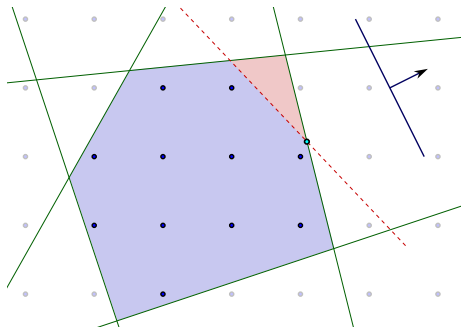
Cuts

$$\begin{array}{ll} \min & c^T x \\ \text{s.t.} & Ax \geq b \\ & \cancel{x_j \in \mathbb{Z}, \text{ for } j \in J} \end{array}$$

(LP)

(cut)

$$\alpha x \geq 1$$



Single-row cuts

From one (re)formulation of the problem

$$\begin{array}{ll} \min & \bar{c}^T x \\ \text{(MIP)} \quad \text{s.t.} & \bar{A}x \geq \bar{b} \\ & x_J \in \mathbb{Z} \end{array}$$

we extract **one** constraint $\bar{A}_i x \geq \bar{b}_i$.

- ▶ Knowing that $x_j \in \mathbb{Z}$, we construct a stronger inequality.
- ▶ In some cases, the cut can *separate* a given MIP-infeasible point x^* .

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Two-row cuts

From one (re)formulation of the problem

$$\begin{array}{ll} \min & \bar{c}^T x \\ \text{(MIP)} \quad \text{s.t.} & \bar{A}x = \bar{b} \\ & x \geq 0 \\ & x_J \in \mathbb{Z} \end{array}$$

we extract **two** constraints

$$\begin{array}{rclcl} x_1 & + & \sum_j \bar{a}_{1j}s_j & = & f_1 & x_1, x_2 \in \mathbb{Z} \\ & + & x_2 + \sum_j \bar{a}_{2j}s_j & = & f_2 & s_j \in \mathbb{R}_+ \end{array},$$

As a vector equation,

$$(P_I) \quad x = f + \sum_j r^j s_j, \quad \begin{array}{l} x \in \mathbb{Z}^2 \\ s \in \mathbb{R}_+^n \end{array}$$

In case (MIP) describes the optimal simplex tableau,
 $(x_{LP}^*, s_{LP}^*) = (f, 0)$.

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$$\begin{array}{rcl} x_1 & + & \sum_j \bar{a}_{1j} s_j = f_1 \\ + x_2 + \sum_j \bar{a}_{2j} s_j & = & f_2 \end{array}, \quad \begin{array}{l} x_1, x_2 \in \mathbb{Z} \\ s_j \in \mathbb{R}_+ \end{array}$$

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The two-row model

$$(MIP) \begin{cases} \bar{A}x = \bar{b} \\ x \geq 0 \\ x_J \in \mathbb{Z} \end{cases} \quad (P_I) \begin{cases} x = f + \sum_j r^j s_j \\ x \in \mathbb{Z}^2 \\ s \in \mathbb{R}_+^n \end{cases}$$

From (MIP) to (P_I) we dropped:

- ▶ all equality constraints except two
- ▶ the integrality constraints on all variables except two
- ▶ the nonnegativity constraints on these two variables

Therefore,

- ▶ (P_I) is a **relaxation** of (MIP), i.e. $(MIP) \subseteq (P_I)$.
- ▶ Any valid inequality for P_I is valid for MIP.

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Problem statement

The two-row model

$$\begin{aligned}x &= f + \sum_j r^j s_j \\ x &\in \mathbb{Z}^2 \\ s_j &\geq 0\end{aligned}$$

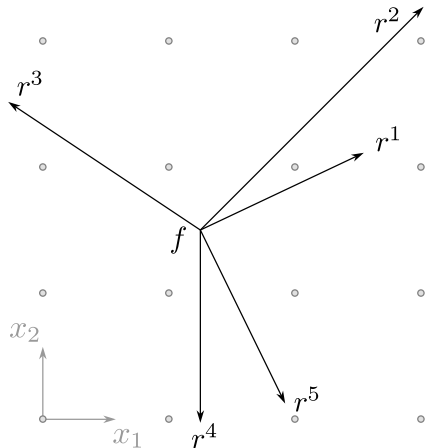
We want to separate

$$(x_1, x_2, s_1, \dots) = (f_1, f_2, 0, \dots).$$

Consider

$$\alpha_1 s_1 + \dots + \alpha_n s_n \geq 1,$$

with $v^i = f + \frac{1}{\alpha_i} r^i$, $\alpha_i \geq 0$.



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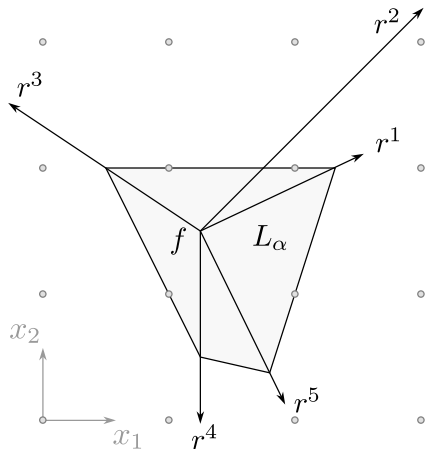
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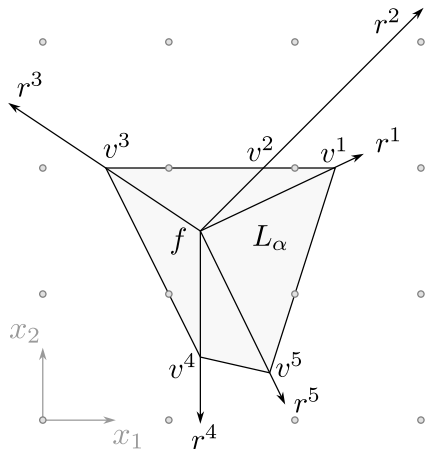
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The two-row separation problem

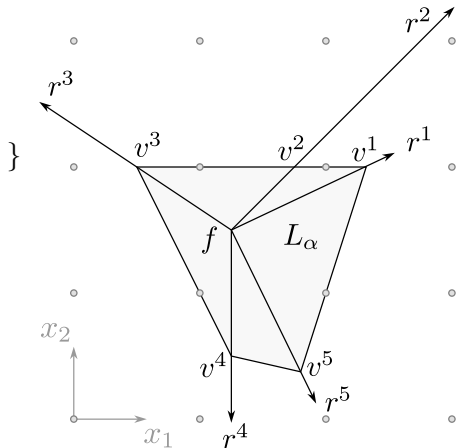
We have a model $P_I :=$

$$\left\{ \begin{array}{lcl} (x, s) : & x & = f + \sum_j r^j s_j \\ & x & \in \mathbb{Z}^2 \\ & s_j & \geq 0 \end{array} \right\}$$

and the general form of a cut

$$\alpha_1 s_1 + \dots + \alpha_n s_n \geq 1,$$

- ▶ How to compute a valid α ?
- ▶ How to choose among valid α s?



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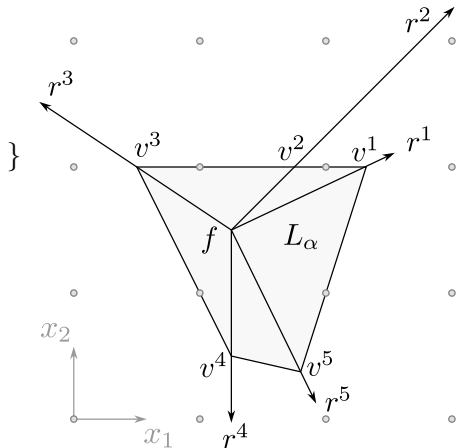
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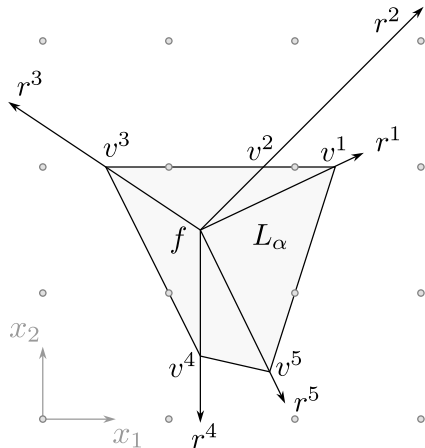
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Lattice-free sets – the LP intuition

Given $\bar{x} \in \mathbb{Z}^2$, we want, for all $s \in \mathbb{R}_+^n$ such that $\bar{x} = f + Rs$, that

$$\alpha_1 s_1 + \dots + \alpha_n s_n \geq 1$$

i.e. we want

$$\begin{array}{ll} \min & \alpha_1 s_1 + \dots + \alpha_n s_n \quad \geq 1 \\ \text{s.t.} & Rs = \bar{x} - f \\ & s \geq 0 \end{array}$$

therefore, for all $i, j, s_i^{\bar{x}}, s_j^{\bar{x}}$ such that $\bar{x} = f + s_i^{\bar{x}} r^i + s_j^{\bar{x}} r^j$, we must have

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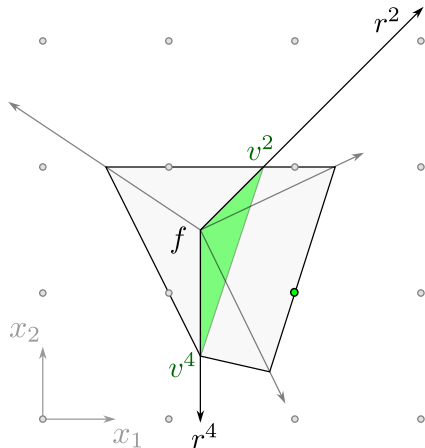
Lattice-free sets – the geometrical intuition

Given $\bar{x} \in \mathbb{Z}^2$,

for all i, j : $\bar{x} \in f + \text{cone}(r^i, r^j)$,

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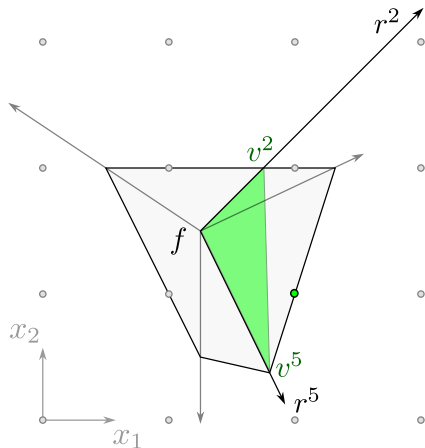
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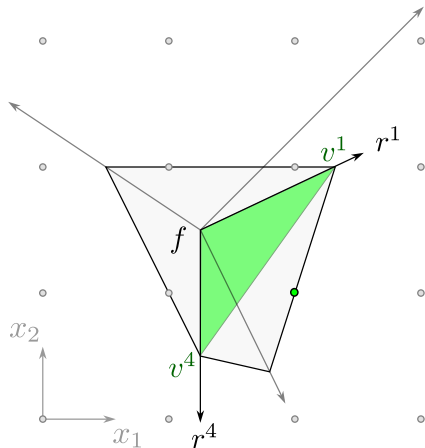
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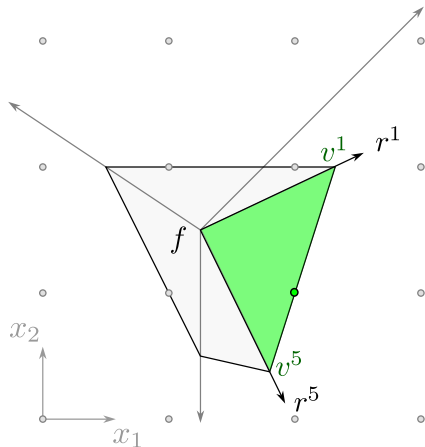
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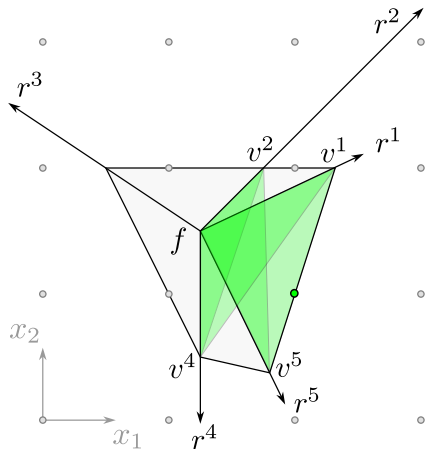
Lattice-free sets – the intuition, for all x

For all $x \in \mathbb{Z}^2$,

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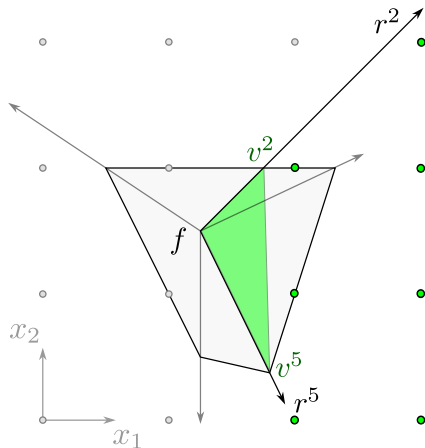
Lattice-free sets – the intuition, for every cone

For all i, j ,

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Lattice-free sets – the set \mathcal{X}_{ij}

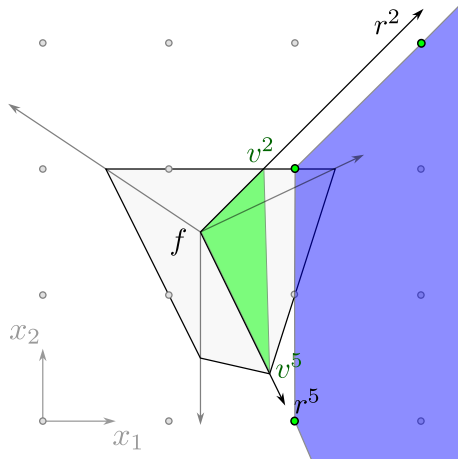
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- ▶ we can restrict $x \in \mathbb{Z}^2$ to $x \in \mathcal{X}_{ij}$ where \mathcal{X}_{ij} is the set of the vertices of $\mathbb{Z}^2 \cap (f + \text{conv}(r^i, r^j))$.



Polarity

Let $P \subseteq \mathbb{R}^N$ be a polyhedron and $Q \subseteq \mathbb{R}^N$ its polar.

There is a correspondance between

Extreme point $\bar{x} \in P$ and Facet of Q : $\bar{x}^T a \geq 1$

Extreme ray $\bar{x} \in P$ and Facet of Q : $\bar{x}^T a \geq 0$

Facet of P : $\bar{a}^T x \geq 1$ and Extreme point $\bar{a} \in Q$

Facet of P : $\bar{a}^T x \geq 0$ and Extreme ray $\bar{a} \in Q$

Polarity, applied

- ▶ We have a polyhedron

$$\text{conv}(P_I) = \text{conv} \left(\left\{ (x, s) \in \mathbb{Z}^2 \times \mathbb{R}_+^n \mid x = f + \sum_j r^j s_j \right\} \right).$$

- ▶ $\text{conv}(P_I) \subseteq \mathbb{R}^{2+n}$ is of dimensionality n .
- ▶ We know the extreme points and rays of $\text{conv}(P_I)$.
- ▶ We can build the polar $Q \subseteq \mathbb{R}^n$ of $\text{conv}(P_I)$.
- ▶ We can optimize over Q to find facets $\text{conv}(P_I)$.

| | | |
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| Extreme point $\bar{x} \in \text{conv}(P_I)$ | \longrightarrow | Facet of Q : $\bar{x}^T \alpha \geq 1$ |
| Extreme ray $\bar{x} \in \text{conv}(P_I)$ | \longrightarrow | Facet of Q : $\bar{x}^T \alpha \geq 0$ |
| | | $\downarrow \downarrow$ |
| Facet of $\text{conv}(P_I)$: $\bar{\alpha}^T x \geq 1$ | \longleftarrow | Extreme point $\bar{\alpha} \in Q$ |
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- ▶ $\text{conv}(P_I) \subseteq \mathbb{R}^{2+n}$ is of dimensionality n .
- ▶ We know the extreme points and rays of $\text{conv}(P_I)$.
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- ▶ We can optimize over Q to find facets $\text{conv}(P_I)$.

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Finding facets of $\text{conv } P_I$

The polar of $\text{conv}(P_I)$ is

$$Q = \{ \alpha \in \mathbb{R}_+^n \mid \forall i, j, \forall x \in \mathcal{X}_{ij}, \quad s_i^x \alpha_i + s_j^x \alpha_j \geq 1 \}.$$

We find facets of $\text{conv}(P_I)$ by choosing an objective function $c^T \alpha$ and optimizing over Q :

$$\begin{aligned} \min \quad & c^T \alpha \\ \text{s.t.} \quad & s_i^x \alpha_i + s_j^x \alpha_j \geq 1, \quad \forall i, j, \forall x \in \mathcal{X}_{ij} \\ & \alpha \geq 0 \end{aligned}$$

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New developments

Complexity of writing the polar (1)

- ▶ For each cone, compute the integer hull.
 - ▶ For each vertex of each integer hull, compute its representation in the corresponding cone and write one inequality of the polar.
1. The complexity is quadratic in the number of rays.
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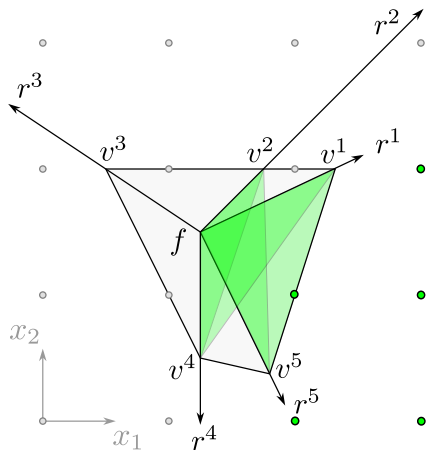
The complexity of the polar – the intuition

$$P_I = \{(x, s) \in \mathbb{Z}^2 \times \mathbb{R}_+^n : \\ x = f + \sum_{j=1}^n r^j s_j\}$$

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$$L_\alpha = \text{conv}(\{f, v^1, \dots, v^n\}) \\ \text{with } v^i = f + \frac{1}{\alpha_i} r^i$$

$$Q' = \{ \alpha \in \mathbb{R}_+^n \mid \forall i, \forall x \in \mathcal{X}_{i,i+1}, \\ s_i^x \alpha_i + s_{i+1}^x \alpha_{i+1} \geq 1 \}$$



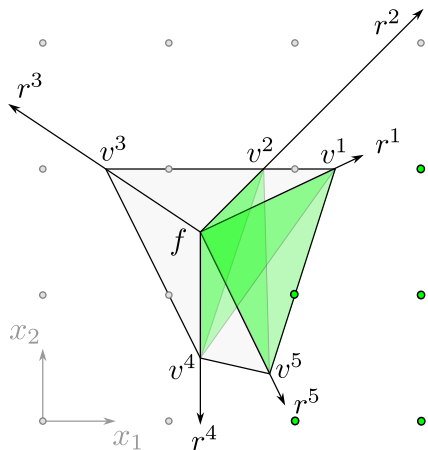
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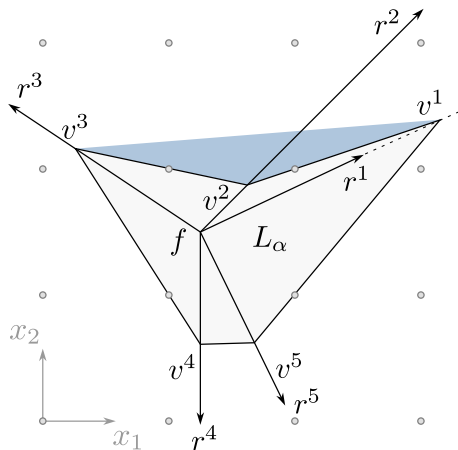
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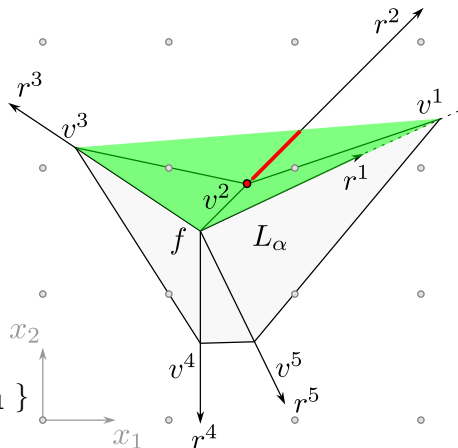
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$$\text{Note: } r^j = \lambda_i^j r^i + \lambda_k^j r^k$$



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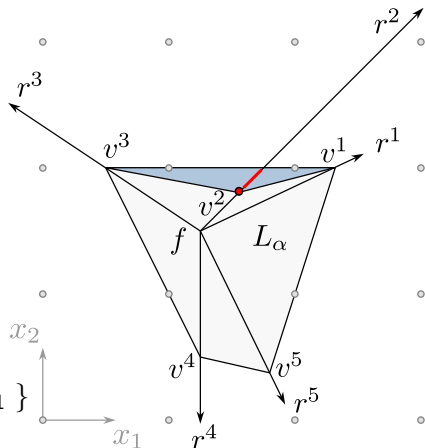
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► What is $Q \setminus \overline{Q}$?

The complexity of the polar – the theory

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Theorem

$\overline{Q} \subseteq Q$, and all vertices of Q are in \overline{Q} .

Corollary

If $c > 0$, $\min_{\text{s.t. } \alpha \in Q} c^T \alpha$ and $\min_{\text{s.t. } \alpha \in \overline{Q}} c^T \alpha$ share the same set of optimal solutions.

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Complexity of writing the polar (2)

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1. The complexity is ~~quadratic~~ **linear** in the number of rays.
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Can we avoid the integer hulls \mathcal{X}_{ij} ?

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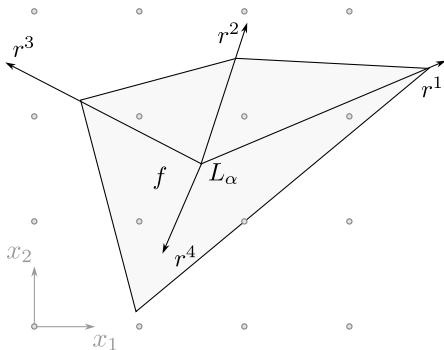
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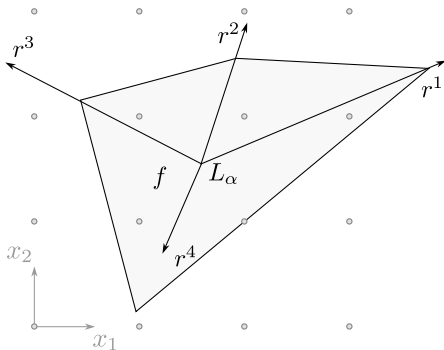
Separation algorithm

$$S := S_0$$
$$\text{do } \{$$
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$$\text{s.t. } \alpha \in \overline{Q}(S)$$
$$\text{if } \alpha \in \overline{Q}$$
$$\text{OK, valid cut, exit.}$$
$$\text{else}$$
$$\text{Find a constraint of } \overline{Q}$$
$$\text{violated by } \alpha.$$
$$\text{Add constraints to } S.$$
$$\}$$



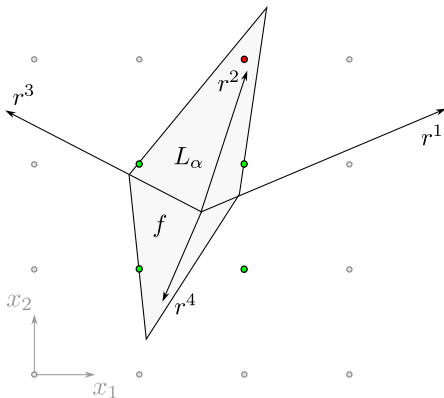
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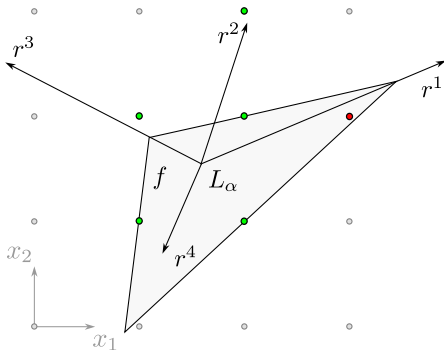
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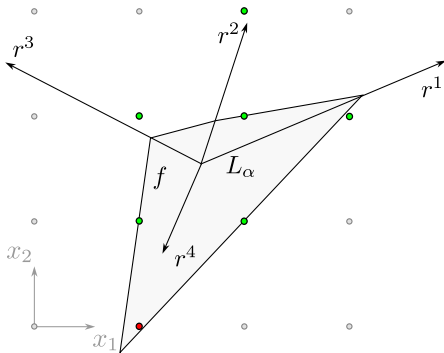
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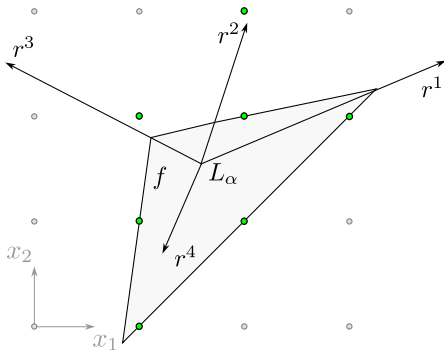
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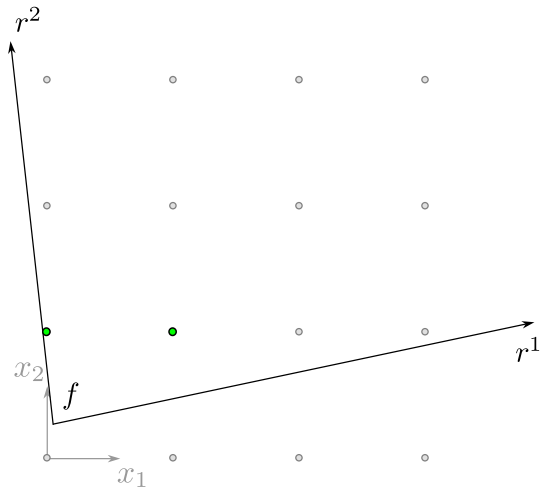


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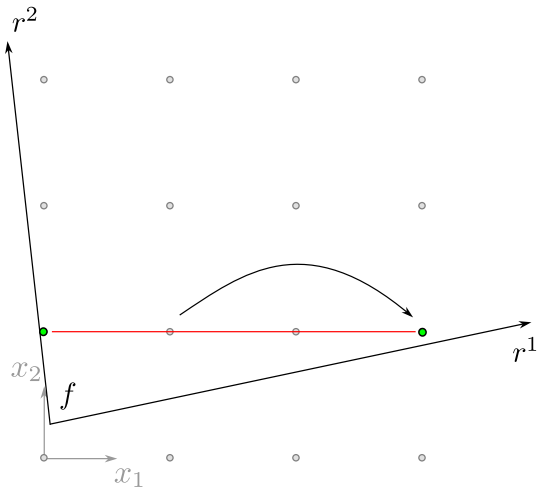
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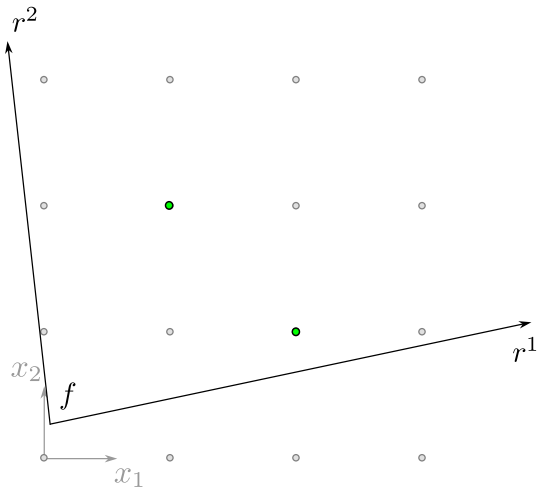
Integer pair extension



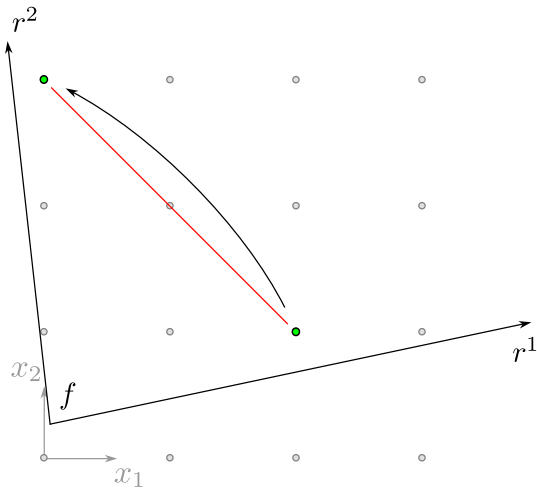
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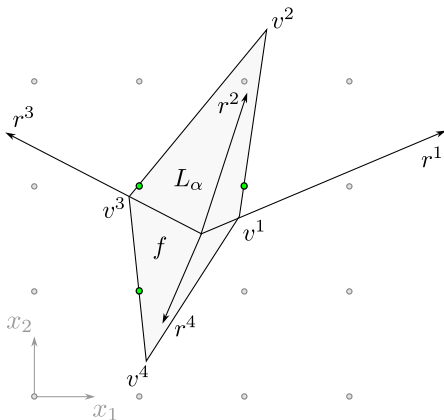


Integer pair extension



The oracle

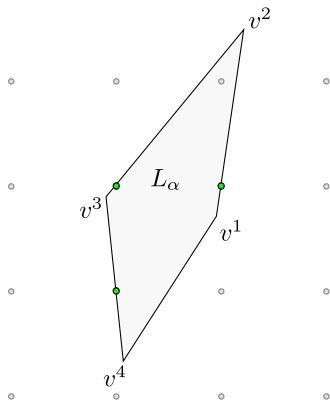
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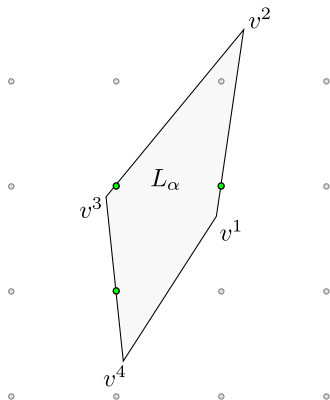
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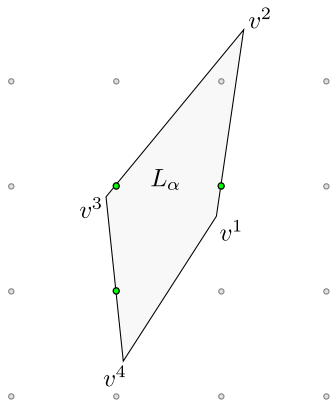
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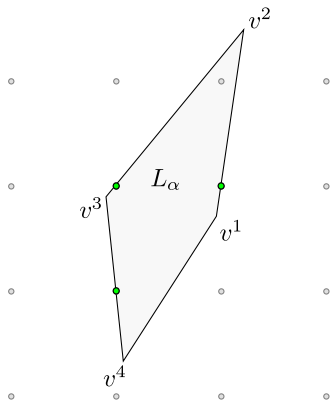
- ▶ possible in polynomial time for any fixed dimension d (Barvinok's algorithm)
- ▶ we are in dimension two
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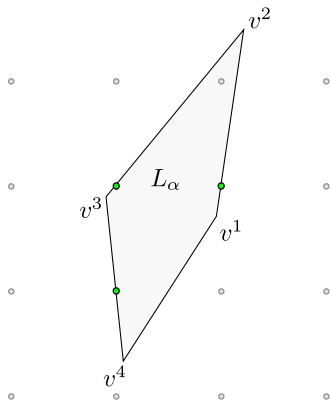
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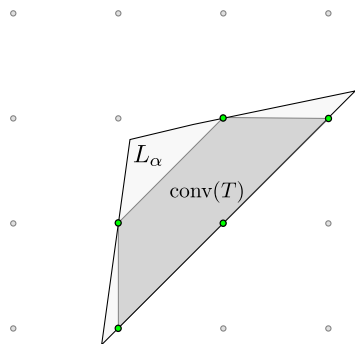


The oracle: $\text{conv}(T)$

Find an integer point in $\text{interior}(L_\alpha)$ or prove that L_α is lattice-free.

1. Consider the convex hull $\text{conv}(T)$ of the known tight integer points:
 $T := S \cap \text{boundary}(L_\alpha)$.

- ▶ we triangularize $\text{conv}(T)$
- ▶ we want to find integer points on integer segments and integer triangles
- ▶ possible with modulo arithmetic

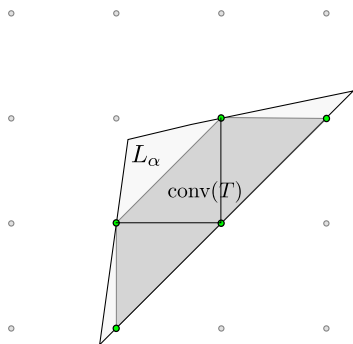


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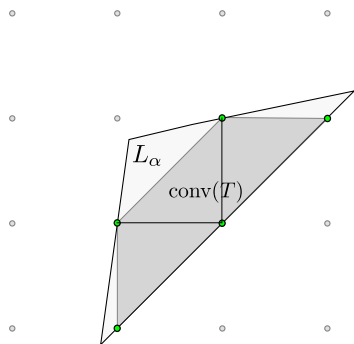


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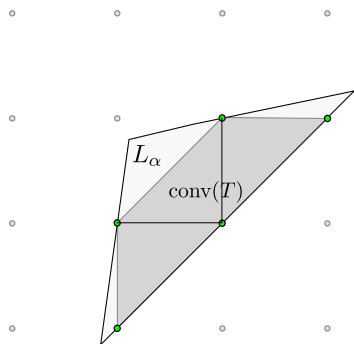


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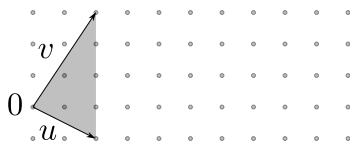


The oracle: $\text{conv}(T)$, continued

Find an integer point in $\text{conv}(T)$ or prove that $\text{conv}(T)$ is lattice-free.

Theorem

Let T be a triangle with vertices $(0, u, v)$ that has interior lattice points and such that $\gcd(u_1, u_2) = \gcd(v_1, v_2) = 1$. T has an interior lattice point w such that $w = \frac{\lambda}{\det([u|v])}u + \frac{1}{\det([u|v])}v$ with $\lambda \in \mathbb{Z}_+$.



We therefore build w by solving the diophantine system

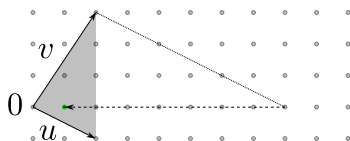
$$\begin{cases} \lambda u_1 + v_1 = k_1 \det([u|v]) \\ \lambda u_2 + v_2 = k_2 \det([u|v]) \end{cases}, \lambda, k_1, k_2 \in \mathbb{Z}$$

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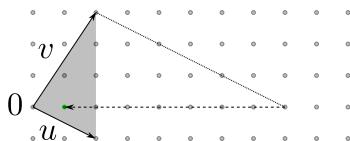
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2. Assume $\text{conv}(T)$ lattice-free.

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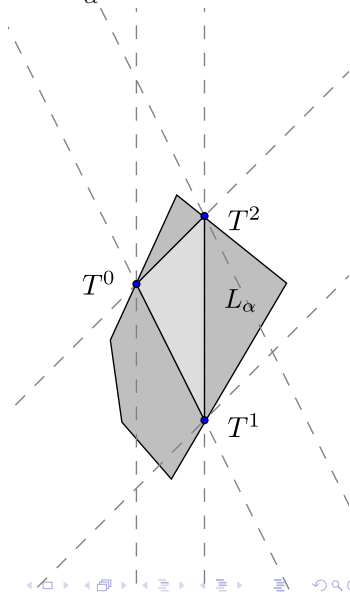
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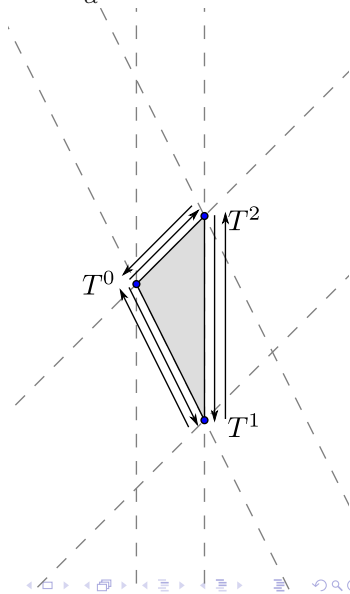
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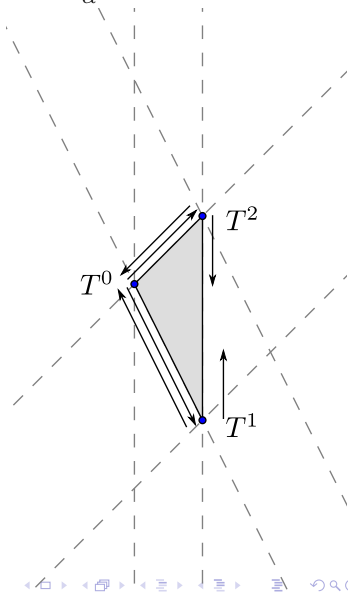
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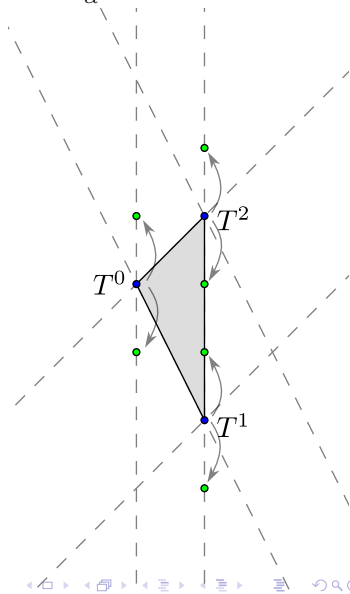
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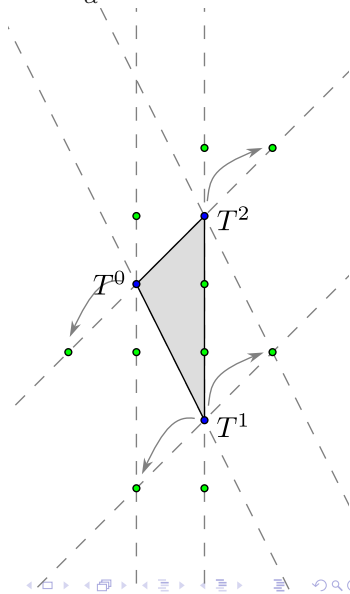
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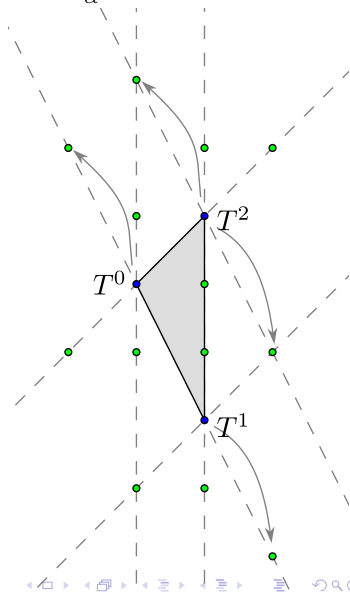
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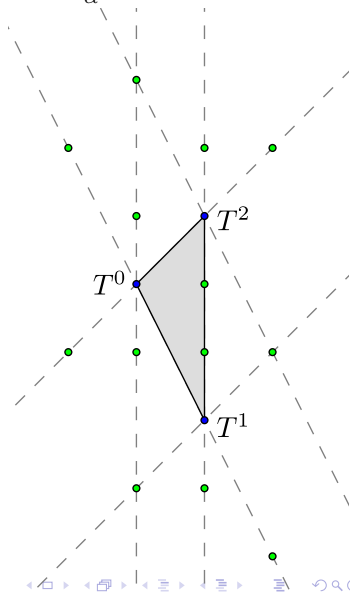
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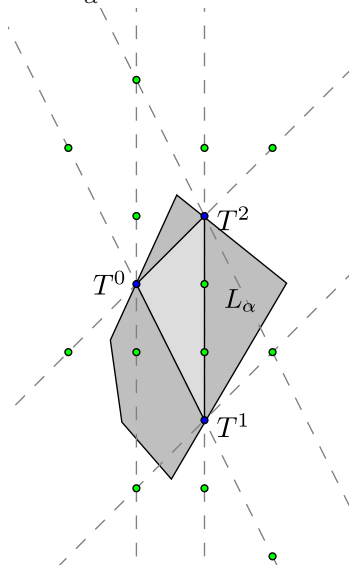
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Results

Preliminary Computational results

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| MIPLIB 3 | 18ms | 99.84% | 1.12 | 39 |
| MIPLIB 2003 | 34ms | 99.95% | 1.17 | 30 |

| | two-row | | | CPLEX | |
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- ▶ means for driving towards deep cuts (with $c^T \alpha$)

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Future directions

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- ▶ objective function
- ▶ basis choice: what is a good basis?
- ▶ basis choice: impact of a pivot on Q
- ▶ choice of the rows
- ▶ separation of $x \neq x_{LP}^*$
- ▶ cut handling
- ▶ (algorithm complexity)
- ▶ strengthening (lifting)
- ▶ more than two rows