Math 115 Spring 2015: Assignment 8

Solutions

 $1. \ {\rm Let}$

$$A = \left[\begin{array}{rrrr} 1 & 6 & -3 \\ 0 & 4 & 0 \\ -3 & 6 & 1 \end{array} \right].$$

(a) [5 marks] Find the eigenvalues of A. For each eigenvalue, give the algebraic multiplicity, determine a basis of the corresponding eigenspace, and give the geometric multiplicity.

Solution:

$$det(A - \lambda I) = det \begin{bmatrix} 1 - \lambda & 6 & -3 \\ 0 & 4 - \lambda & 0 \\ -3 & 6 & 1 - \lambda \end{bmatrix}$$
$$= (4 - \lambda).(-1)^{2+2}.det \begin{bmatrix} 1 - \lambda & -3 \\ -3 & 1 - \lambda \end{bmatrix}$$
$$= (4 - \lambda).((1 - \lambda).(1 - \lambda) - (-3).(-3))$$
$$= (4 - \lambda).(1 + \lambda^2 - 2\lambda - 9)$$
$$= (4 - \lambda).(\lambda^2 - 2\lambda - 8)$$

We need to find the roots of $\lambda^2 - 2\lambda - 8$. The discriminant is given by

$$\delta = 2^2 - 4.1.(-8) = 4 + 32 = 36$$

and the roots are

$$\lambda = \frac{-(-2) \pm \sqrt{36}}{2.1} = \frac{2 \pm 6}{2}$$

so 4 and -2. Therefore,

$$\det(A - \lambda I) = (4 - \lambda)(4 - \lambda)(2 + \lambda).$$

First eigenvalue: $\lambda_1 = 4$, algebraic multiplicity 2. The system

$$\begin{bmatrix} -3 & 6 & -3 \\ 0 & 0 & 0 \\ -3 & 6 & -3 \end{bmatrix} \vec{v} = \vec{0}$$

has the augmented matrix

$$\begin{bmatrix} -3 & 6 & -3 & 0 \\ 0 & 0 & 0 & 0 \\ -3 & 6 & -3 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

 \mathbf{SO}

$$\vec{v}_1 = s \begin{bmatrix} 2\\1\\0 \end{bmatrix} + t \begin{bmatrix} -1\\0\\1 \end{bmatrix}, \quad s, t \in \mathbb{R}$$

And a basis of the eigenspace associated to eigenvalue 4 is given by $\left\{ \begin{bmatrix} 2\\1\\0 \end{bmatrix}, \begin{bmatrix} -1\\0\\1 \end{bmatrix} \right\}$. The geometric

multiplicity of this eigenvalue is 2.

Second eigenvalue: $\lambda_2 = -2$, algebraic multiplicity 2. The system

$$\begin{bmatrix} 3 & 6 & -3 \\ 0 & 6 & 0 \\ -3 & 6 & 3 \end{bmatrix} \vec{v} = \vec{0}$$

has the augmented matrix

$$\begin{bmatrix} 3 & 6 & -3 & 0 \\ 0 & 6 & 0 & 0 \\ -3 & 6 & 3 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

 \mathbf{SO}

$$\vec{v}_2 = t \begin{bmatrix} 1\\0\\1 \end{bmatrix}, \quad t \in \mathbb{R}$$

And a basis of the eigenspace associated to eigenvalue -2 is given by $\left\{ \begin{bmatrix} 1\\0\\1 \end{bmatrix} \right\}$. The geometric multiplicity of this eigenvalue is 1.

plicity of this eigenvalue is 1.

(b) [1 mark] Diagonalize A by finding an invertible matrix P and a diagonal matrix D such that $P^{-1}AP = D$

Solution: We collect the three basis vectors for the eigenspaces of all eigenvalues of A found above as columns of P. We construct D as a matrix whose diagonal elements are the corresponding eigenvalues.

$$P = \begin{bmatrix} 1 & 2 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \quad D = \operatorname{diag}(4, 4, -2) = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & -2 \end{bmatrix}.$$

2. [5 marks] Determine a matrix $B \in \mathbb{R}^{2 \times 2}$ for which $\begin{bmatrix} 3 \\ -2 \end{bmatrix}$ and $\begin{bmatrix} -4 \\ 3 \end{bmatrix}$ are eigenvectors, with corresponding eigenvalue -4 and 2, respectively.

Solution:

$$P^{-1}BP = \operatorname{diag}(\lambda_1, \lambda_2)$$

$$B = P \operatorname{diag}(\lambda_1, \lambda_2)P^{-1}$$

$$B = \begin{bmatrix} 3 & -4 \\ -2 & 3 \end{bmatrix} \operatorname{diag}(-4, 2) \begin{bmatrix} 3 & -4 \\ -2 & 3 \end{bmatrix}^{-1}$$

$$B = \begin{bmatrix} 3 & -4 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} -4 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 3 & -4 \\ -2 & 3 \end{bmatrix}^{-1}$$

We compute the inverse of $\begin{bmatrix} 3 & -4 \\ -2 & 3 \end{bmatrix}$: $\begin{bmatrix} 3 & -4 & | & 1 & 0 \\ -2 & 3 & | & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | & 3 & 4 \\ 0 & 1 & | & 2 & 3 \end{bmatrix}$

 \mathbf{SO}

$$B = \begin{bmatrix} 3 & -4 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} -4 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 3 & 4 \\ 2 & 3 \end{bmatrix}$$
$$= \begin{bmatrix} 3 & -4 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} -12 & -16 \\ 4 & 6 \end{bmatrix}$$
$$= \begin{bmatrix} -52 & -72 \\ 36 & 50 \end{bmatrix}$$

3. [4 marks] Let $C \in \mathbb{R}^{n \times n}$ be a diagonalizable matrix that has *n* distinct eigenvalues. Prove that det(*C*) is the product of the *n* eigenvalues of *C*.

Solution: Since C is diagonalizable, there exists an invertible matrix $R \in \mathbb{R}^{n \times n}$ such that

$$R^{-1}CR = \operatorname{diag}(\nu_1, \ldots, \nu_n)$$

where ν_1, \ldots, ν_n are the eigenvalues of C. Then, $C = R \operatorname{diag}(\nu_1, \ldots, \nu_n) R^{-1}$ and

$$det(C) = det(R) det(diag(\nu_1, \dots, \nu_n)) det(R^{-1})$$

= $det(R) det(diag(\nu_1, \dots, \nu_n)) \frac{1}{det(R)}$
= $det(diag(\nu_1, \dots, \nu_n))$
= $\nu_1 \dots \nu_n$

4. [5 marks] Let $G \in \mathbb{R}^{n \times n}$ be a diagonalizable matrix such that $Q^{-1}GQ = \text{diag}(\mu_1, \dots, \mu_n)$. Find an expression of G^4 that does not involve G (it may involve, Q and μ_1, \dots, μ_n). Give the eigenvalues of G^4 . Solution:

$$G = Q \operatorname{diag}(\mu_1, \dots, \mu_n) Q^{-1}$$

 \mathbf{SO}

$$\begin{aligned} G^k &= (Q \operatorname{diag}(\mu_1, \dots, \mu_n) Q^{-1}) \\ &= Q \operatorname{diag}(\mu_1, \dots, \mu_n) Q^{-1} \\ &= Q \operatorname{diag}(\mu_1, \dots, \mu_n) \operatorname{diag}(\mu_1, \dots, \mu_n) \operatorname{diag}(\mu_1, \dots, \mu_n) \operatorname{diag}(\mu_1, \dots, \mu_n) Q^{-1} \\ &= Q \operatorname{diag}(\mu_1, \dots, \mu_n)^4 Q^{-1} \end{aligned}$$

$$= Q \operatorname{diag}(\mu_1^4, \dots, \mu_n^4) Q^{-1}$$

The eigenvalues of G^4 are μ_1^4, \ldots, μ_n^4 .