



Transient Stability Closed-Loop Emergency Control

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An emergency control cycle

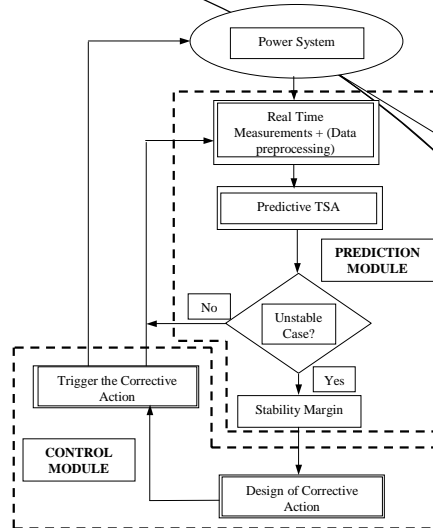
- Data acquisition at power plants and their transmission to the control room,
- Data processing at the control room,
- Order transmission from the control room to the system,
- The order actual implementation.

E-SIME

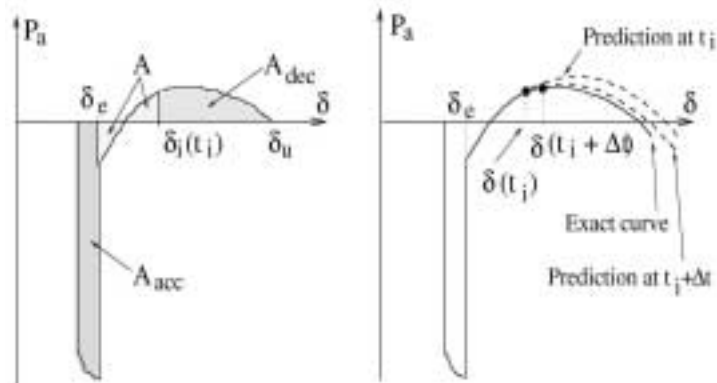
E-SIME is responsible for the data processing at the control room and the processing include: (in)stability prediction and assessment and control action design

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General framework



Prediction module – the principle





Prediction module, ctd. -1

- Predicting the OMIB structure
- Predicting the OMIB swing curve (using weighted least-squares estimation)

$$\hat{P}_a(\delta) = a\delta^2 + b\delta + c$$

- Predicting instability by searching whether the above curve reaches SIME instability conditions

$$\hat{P}_a(\delta_u) = 0, \dot{\hat{P}}_a(\delta_u) > 0$$

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Prediction module, ctd. -2

- Computing of the corresponding margin and time to instability

$$\eta = - \int_{\delta_i}^{\delta_u} \hat{P}_a d\delta - \frac{1}{2} M \omega_i^2$$

$$t_u = t_i + \int_{\delta_i}^{\delta_u} \frac{d\delta}{\sqrt{\frac{2}{M} \int_{\delta_i}^{\delta_u} (-\hat{P}_a d\delta) + \omega_i^2}}$$

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Control module (generation shedding scheme)

- From the predicted swing curves of the individual machines, take the most advanced one(s),
- Compute the margin of the corrected system, if the margin is still unsatisfactory shed another machine(s),

$$\eta = - \int_{\delta_a^{(1)}}^{\delta_a^{(2)}} \hat{P}_a^{(2)} d\delta^{(2)} - \frac{1}{2} M^{(1)} \omega_{cr}^{(1)2}$$

$$\hat{P}_a^{(2)} = a^{(2)} \delta^2 + b^{(2)} \delta + c^{(2)}$$

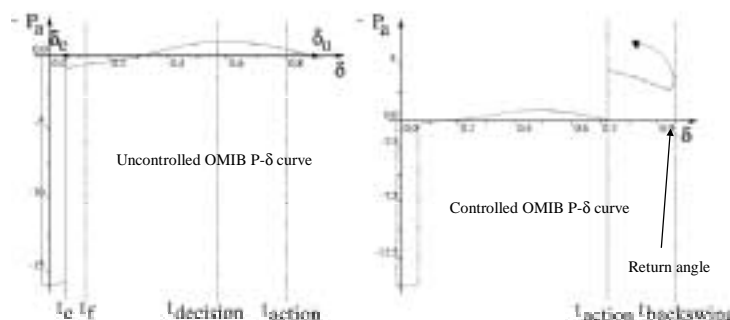
$$\delta^{(2)} = \delta^{(1)}, \quad \hat{P}_a^{(2)} = \hat{P}_a^{(1)} - M^{(1)} \frac{P_{ej}}{M_c^{(1)}}$$

$$x = \int_{\delta_i^{(1)}}^{\delta_a^{(1)}} \frac{d\delta^{(1)}}{\sqrt{\frac{2}{M^{(1)}} \int_{\delta_i}^{\delta} (-\hat{P}_a^{(1)}) d\delta^{(1)} + (\omega_i^{(1)})^2}}$$

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Control module, ctd.

- Continue until the margin becomes satisfactory.
- Once the shedding order is sent, continue monitoring the system.

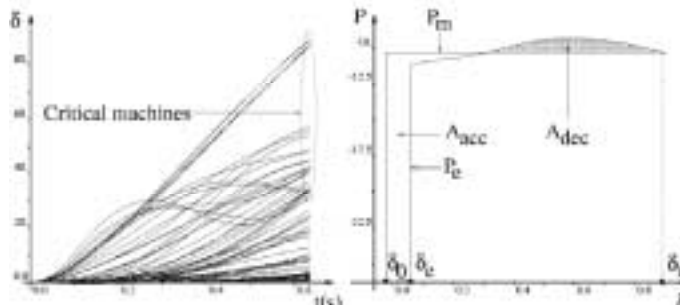


The principle of emergency control

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Simulations – EPRI 88-machine test system



Uncontrolled system

NOTE: Real-time measurements are “artificially” created, on the basis of T-D simulation using ETMSP program. Base case: 350,749 MW.



Controlled system - summary

Preventive SIME:
 - Time to instability
 635 ms
 -Normalized margin
 -1.044 (rad/s)**2

1	2	3	4	5
t_i (ms)	δ_i (rad.)	t_u (ms)	η/M (rad/sec) ²	η/M after shed.
375	1.094	788	-0.60	
395	0.922	676	-0.81	
Corrective decision is taken (3 units shed, 2,463 MW)				
415	0.850	631	-0.88	0.271
435	0.822	614	-0.91	0.115
455	0.813	610	-0.91	0.092
475	0.820	617	-0.91	0.113
495	0.826	622	-0.90	0.151
515	0.836	631	-0.90	0.234
535	0.850	642	-0.89	0.347
555	0.858	649	-0.89	0.376
Corrective action is applied				
575	0.861	652	-0.89	0.352
595	0.860	652	-0.89	0.361
615	0.859	651	-0.89	0.373
635	0.861	652	-0.89	0.384

Simulations - Italian Power System



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An unstable scenario in Italian Power System

- No preliminary network weakening,
- Sequence of events:
 - permanent 3-phase short circuit on the 380 kV line Andria-Brindisi, at 10% distance from Brindisi
 - opening of the line at both ends after 0.3 s from short

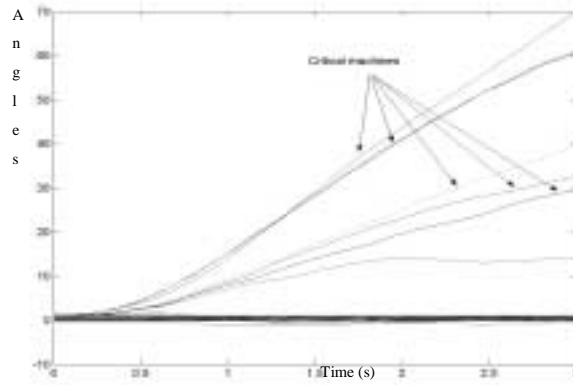
NOTE 1: Scenario simulates a protection malfunctioning or improper setting—typical value for the clearing time 100 ms

NOTE 2: Real-time measurements are “artificially” created, on the basis of time-domain simulation using SICRE-ENEL simulator.

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Simulation results-1

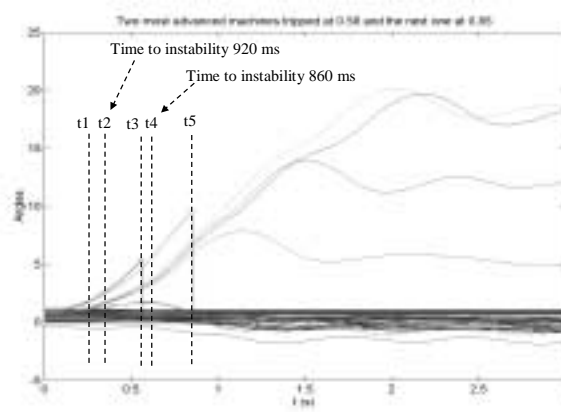


Uncontrolled system

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Simulation results-2



Controlled system

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Controlled system - summary

1	2
Time (ms)	Description
t1=260	The first negative margin, $t_u=920$ ms
t2=360	Margin converged to a constant value
Corrective decision is taken (2 units shed 968 MW)	
t3=560	
Corrective action is applied	
t4=640	Negative margin appeared again, $t_u=860$ ms
Corrective decision is taken (1 unit shed 42 MW)	
t5=850	
Corrective action is applied	

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Ongoing and future research

- Data preprocessing (estimating rotor angles from PMU measurements),
- Appraise of other controls (dynamic breaking, fast valving, etc...),
- SIME-based adaptive emergency control (combining OLEC and CLEC),
- Adaptive emergency control by combining E-SIME and Reinforcement Learning,
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Data preprocessing (Why to estimate rotor angles?)

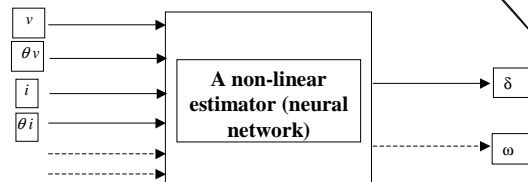
- Rotor angle of the synchronous generator is the most important quantity in power system transient stability control
- PMU measured quantities are electrical variables and experience fast changes, unlike rotor angles (mechanical variable)
- Wrong or noisy rotor angles may result in wrong E-SIME OMIB structure (prediction module) and wrong determination of control actions (control module)

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Data preprocessing, ctd.

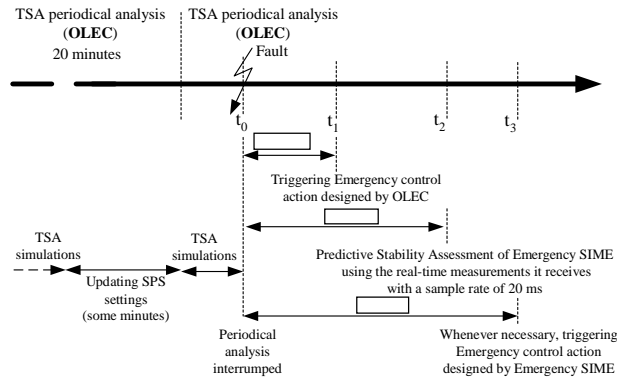
$$f : \{u_t\} \in R^n \Rightarrow \{\delta_t\} \in R^{1(2)}$$



$$\{u_t\} = [v_t, v_{t-1}, \theta_{v_t}, \theta_{v_{t-1}}, i_t, i_{t-1}, \theta_{i_t}, \theta_{i_{t-1}}]^T$$

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Combining OLEC and CLEC



Conclusions

- E-SIME is free from system modeling and parameter uncertainties, location and clearing scenario of the contingency. High computational efficiency,
- The total time required for the whole cycle “prediction-assessment-design and triggering of the action” is expected not to exceed 500-600 ms,
- The applications on the EPRI 88-machines test system and Italian Power System were shown to provide effective control,
- The generation shedding scheme has shown to effectively apply to three other real-world Power Systems (the Hydro-Quebec system(Churchill Falls corridor), the Brazilian Power System (Itaipu site)), and WSCC,
- E-SIME and OLEC have more or less complementary features and assets. Combination of these controls comes quite naturally.