

Discretization of Electromagnetic Problems

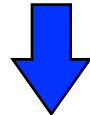
Nodal, edge, face and volume finite elements

Discrete mathematical structure

Continuous problem

Continuous function spaces & domain
Classical and weak formulations

Discretization



Approximation

Discrete problem

Discrete function spaces piecewise defined
in a discrete domain (mesh)

Finite element method

Questions

Classical & weak formulations → ?
Properties of the fields → ?

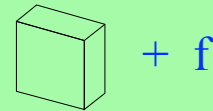
Objective

To build a discrete structure
as similar as possible
as the continuous structure

Discrete mathematical structure

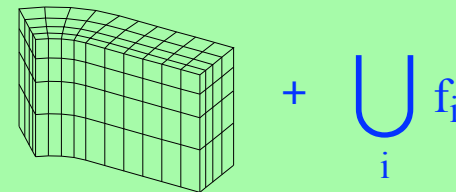
Finite element

Interpolation in a geometric element of simple shape



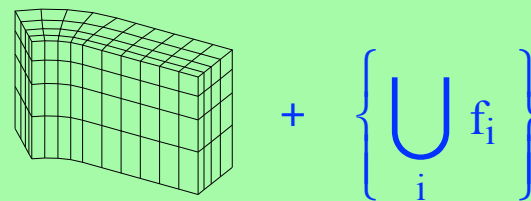
Finite element space

Function space
& Mesh



Sequence of finite element spaces

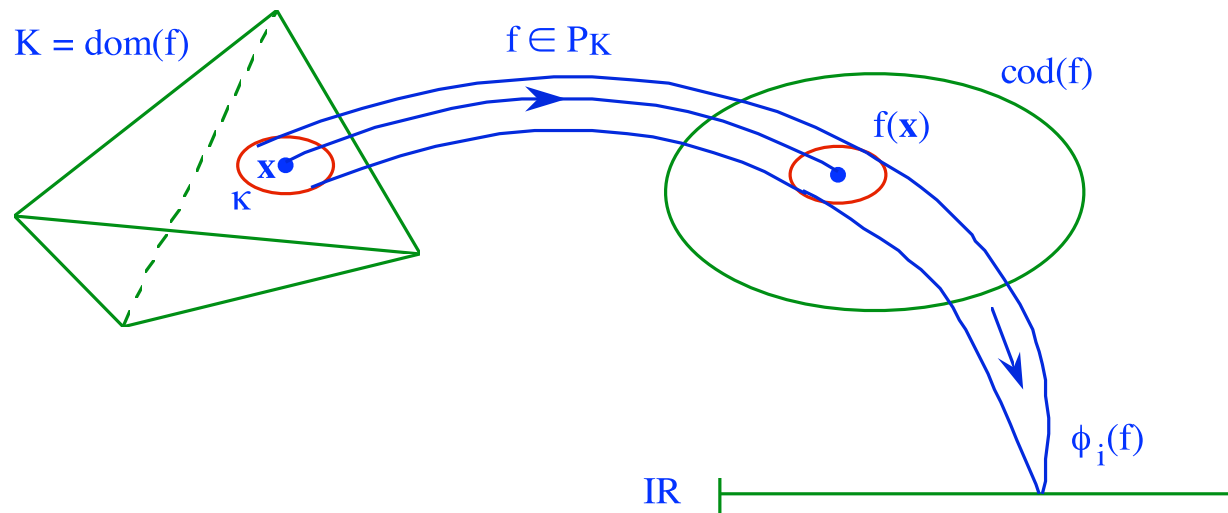
Sequence of function spaces
& Mesh



Finite elements

❖ Finite element $(\mathbf{K}, \mathbf{P}_{\mathbf{K}}, \Sigma_{\mathbf{K}})$

- ◆ \mathbf{K} = domain of space (tetrahedron, hexahedron, prism)
- ◆ $\mathbf{P}_{\mathbf{K}}$ = function space of finite dimension $n_{\mathbf{K}}$, defined in \mathbf{K}
- ◆ $\Sigma_{\mathbf{K}}$ = set of $n_{\mathbf{K}}$ degrees of freedom represented by $n_{\mathbf{K}}$ linear functionals ϕ_i , $1 \leq i \leq n_{\mathbf{K}}$, defined in $\mathbf{P}_{\mathbf{K}}$ and whose values belong to \mathbb{R}



Finite elements

❖ Unisolvance

$\forall u \in P_K$, u is uniquely defined by the degrees of freedom

❖ Interpolation

$$u_K = \sum_{i=1}^{n_K} \phi_i(u) p_i$$

Degrees of freedom

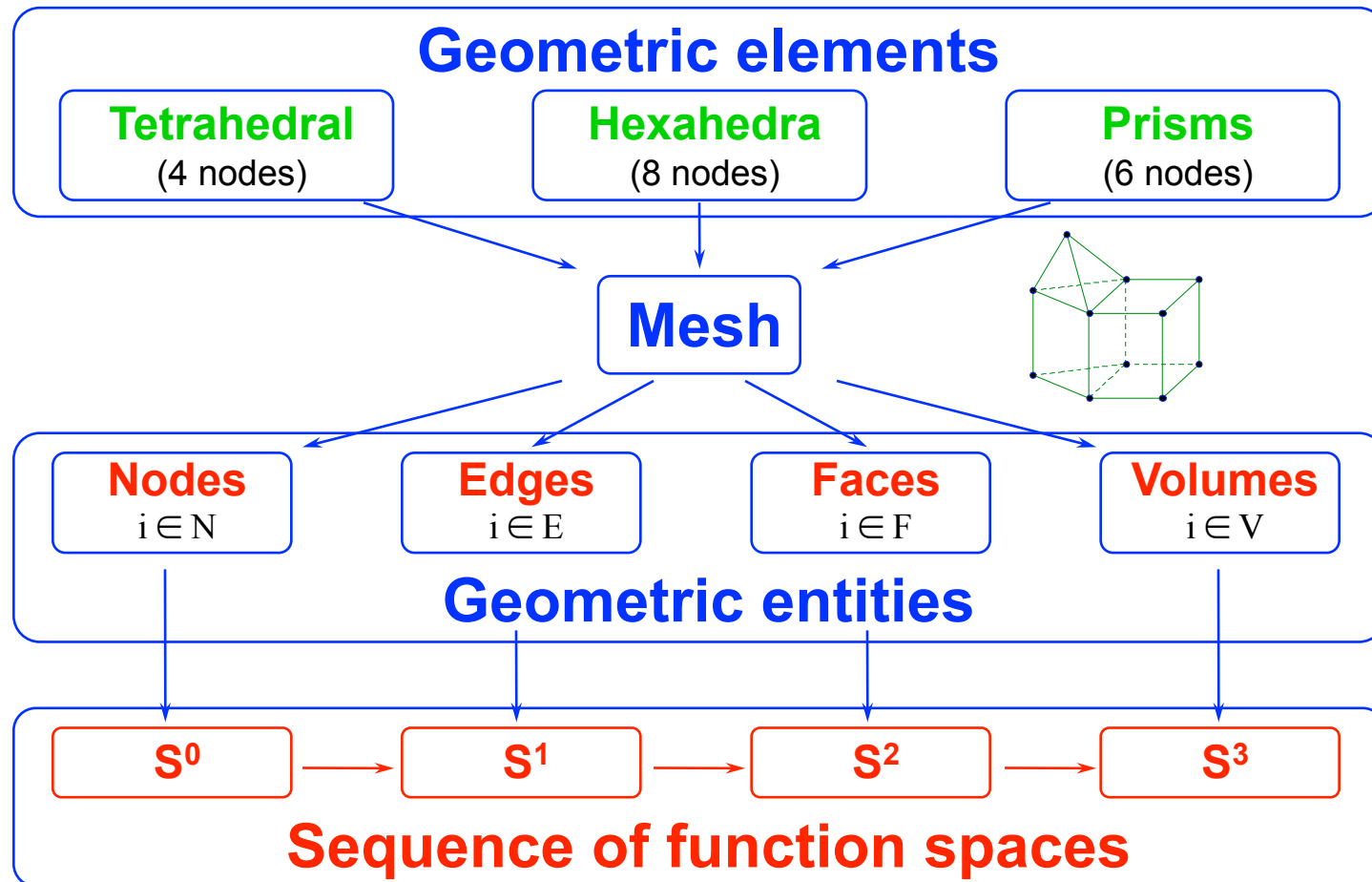
Basis functions

❖ Finite element space

Union of finite elements $(K_j, P_{K_j}, \Sigma_{K_j})$ such as :

- the union of the K_j fill the studied domain (\equiv mesh)
- some continuity conditions are satisfied across the element interfaces

Sequence of finite element spaces



Sequence of finite element spaces

	Functions	Properties	Functionals	Degrees of freedom	
S^0	$\{s_i, i \in N\}$	$s_i(x_j) = \delta_{ij}$ $\forall i, j \in N$	Point evaluation	Nodal value	→ Nodal element
S^1	$\{s_i, i \in E\}$	$\int_j s_i \cdot dl = \delta_{ij}$ $\forall i, j \in E$	Curve integral	Circulation along edge	→ Edge element
S^2	$\{s_i, i \in F\}$	$\int_j s_i \cdot \mathbf{n} ds = \delta_{ij}$ $\forall i, j \in F$	Surface integral	Flux across face	→ Face element
S^3	$\{s_i, i \in V\}$	$\int_j s_i dv = \delta_{ij}$ $\forall i, j \in V$	Volume integral	Volume integral	→ Volume element

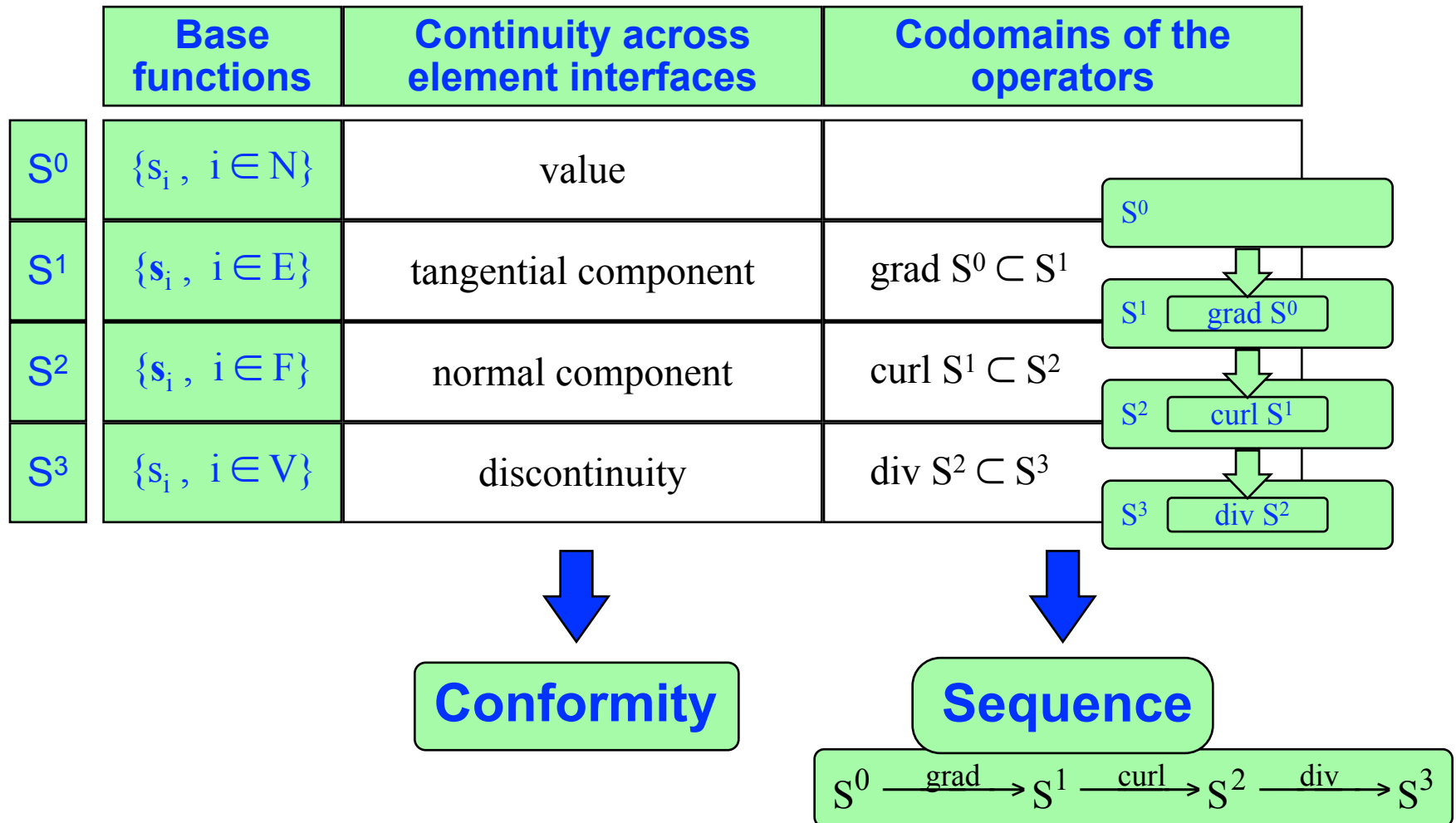
↓
Bases

↓

$$u_K = \sum_i \phi_i(u) s_i$$

↑
Finite elements

Sequence of finite element spaces



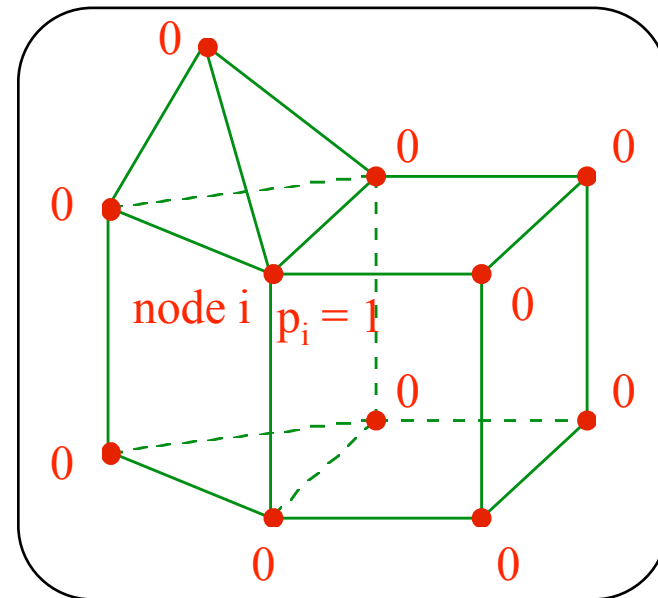
Function spaces S^0 et S^3

For each **node** $i \in \mathbf{N} \rightarrow$ **scalar field**

$$s_i(\mathbf{x}) = p_i(\mathbf{x}) \in S^0$$

$$p_i = \begin{cases} 1 & \text{at node } i \\ 0 & \text{at all other nodes} \end{cases}$$

p_i continuous in Ω



For each **Volume** $v \in \mathbf{V} \rightarrow$ **scalar field**

$$s_v = 1 / \text{vol}(v) \in S^3$$

Edge function space S^1

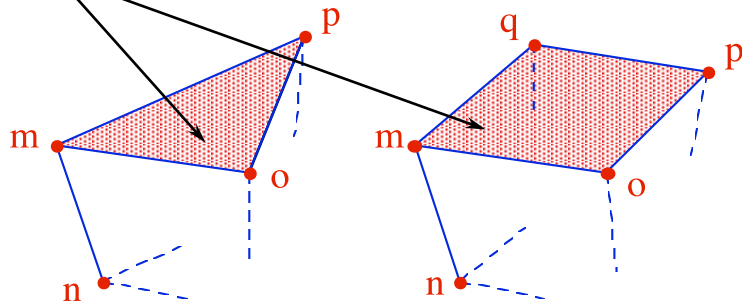
For each **edge** $e_{ij} = \{i, j\} \in E \rightarrow$ **vector field**

$$s_{e_{ij}} = p_j \operatorname{grad} \sum_{r \in N_{F,ji}} p_r - p_i \operatorname{grad} \sum_{r \in N_{F,ij}} p_r$$

$s_e \in S^1$

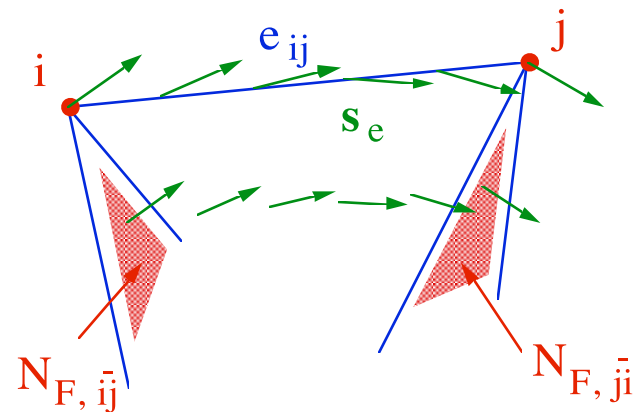
Definition of the set of nodes $N_{F,m\bar{n}}$

$$N_{F,m\bar{n}} = \{i \in N; i \in f_{\operatorname{map}(q)}, o, p, q \neq n\}$$

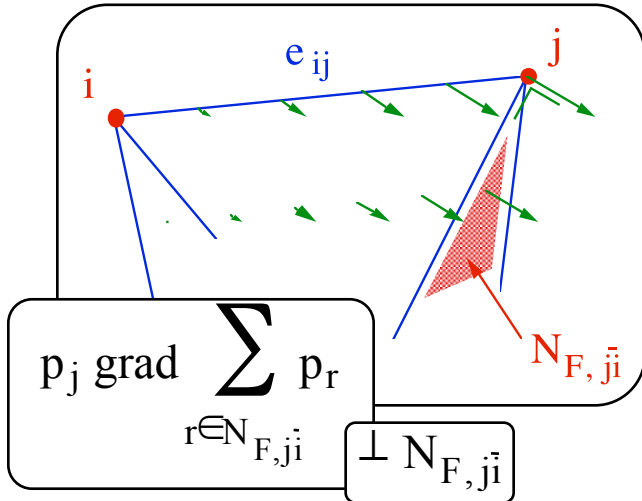


N.B.: In an element : 3 edges/node

Illustration of the vector field s_e

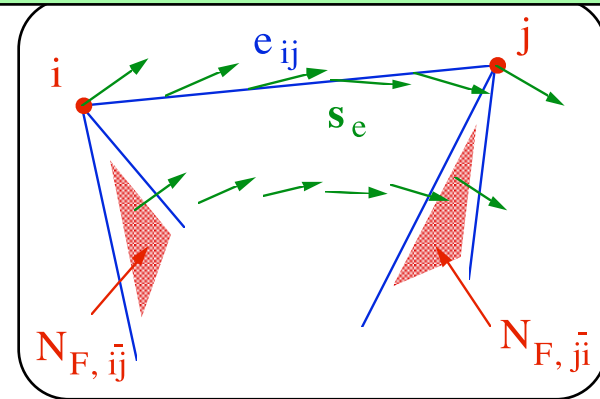
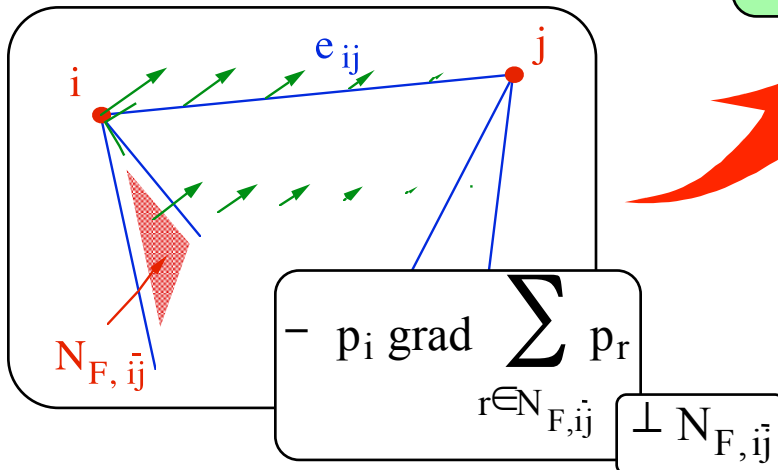


Edge function space S^1



Geometric interpretation
of the vector field s_e

$$s_{e_{ij}} = p_j \text{grad} \sum_{r \in N_{F, \bar{j}i}} p_r - p_i \text{grad} \sum_{r \in N_{F, \bar{i}j}} p_r$$



Function space S^2

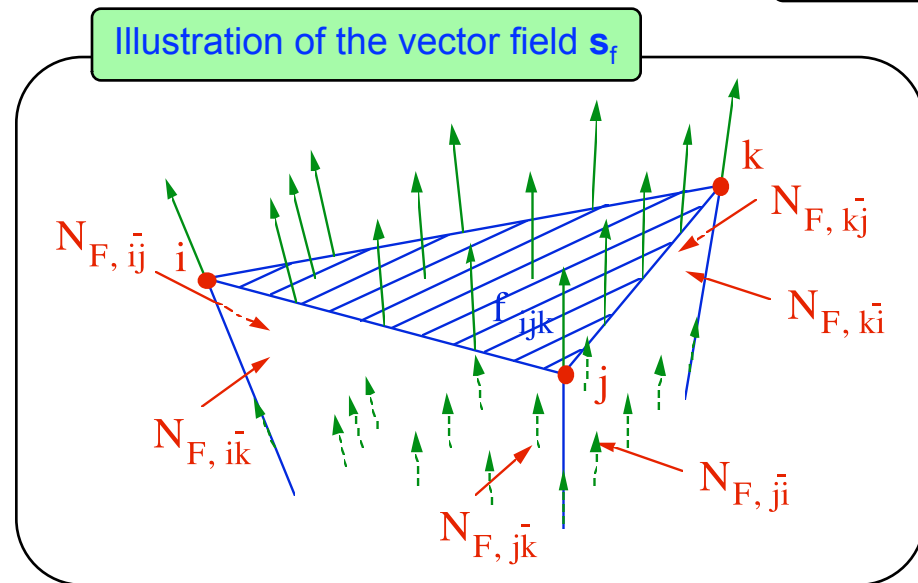
For each facet $f \in F \rightarrow$ vector field

$$f = f_{ijk(l)} = \{i, j, k, (l)\} = \{q_1, q_2, q_3, (q_4)\}$$

$$s_f = a_f \sum_{c=1}^{\#N_c} p_{q_c} \text{grad} \left(\sum_{r \in N_{F, q_c} \bar{q}_{c+1}} p_r \right) \wedge \text{grad} \left(\sum_{r \in N_{F, q_c} \bar{q}_{c-1}} p_r \right)$$

$$s_f \in S^2$$

$$\#N_f = \begin{cases} \blacktriangle & 3 \rightarrow a_f = 2 \\ \blacksquare & 4 \rightarrow a_f = 1 \end{cases}$$



Particular subspaces of S^1

Kernel of the curl operator

$$\mathbf{h} \in S^1(\Omega) ; \text{curl } \mathbf{h} = 0 \text{ in } \Omega_c^C \subset \Omega \rightarrow \mathbf{h} \equiv ?$$

Applications

Ampere equation
in a domain Ω_c^C
without current
($\leftrightarrow \Omega_c$)

Gauged subspace

$$\mathbf{a} \in S^1(\Omega) ; \mathbf{b} = \text{curl } \mathbf{a} \in S^2(\Omega) \rightarrow \mathbf{a} \equiv ?$$

Gauge $\mathbf{a} \cdot \boldsymbol{\omega} = 0$
to fix \mathbf{a}

Gauge condition
on a vector potential

Definition of a
generalized source field \mathbf{h}_s
such that $\text{curl } \mathbf{h}_s = \mathbf{j}_s$

Kernel of the curl operator

Case of simply connected domains

$$H = \{ \mathbf{h} \in S^1(\Omega) ; \text{curl } \mathbf{h} = 0 \text{ in } \Omega_c^C \}$$

$$\mathbf{h} = -\text{grad } \phi \text{ in } \Omega_c^C$$

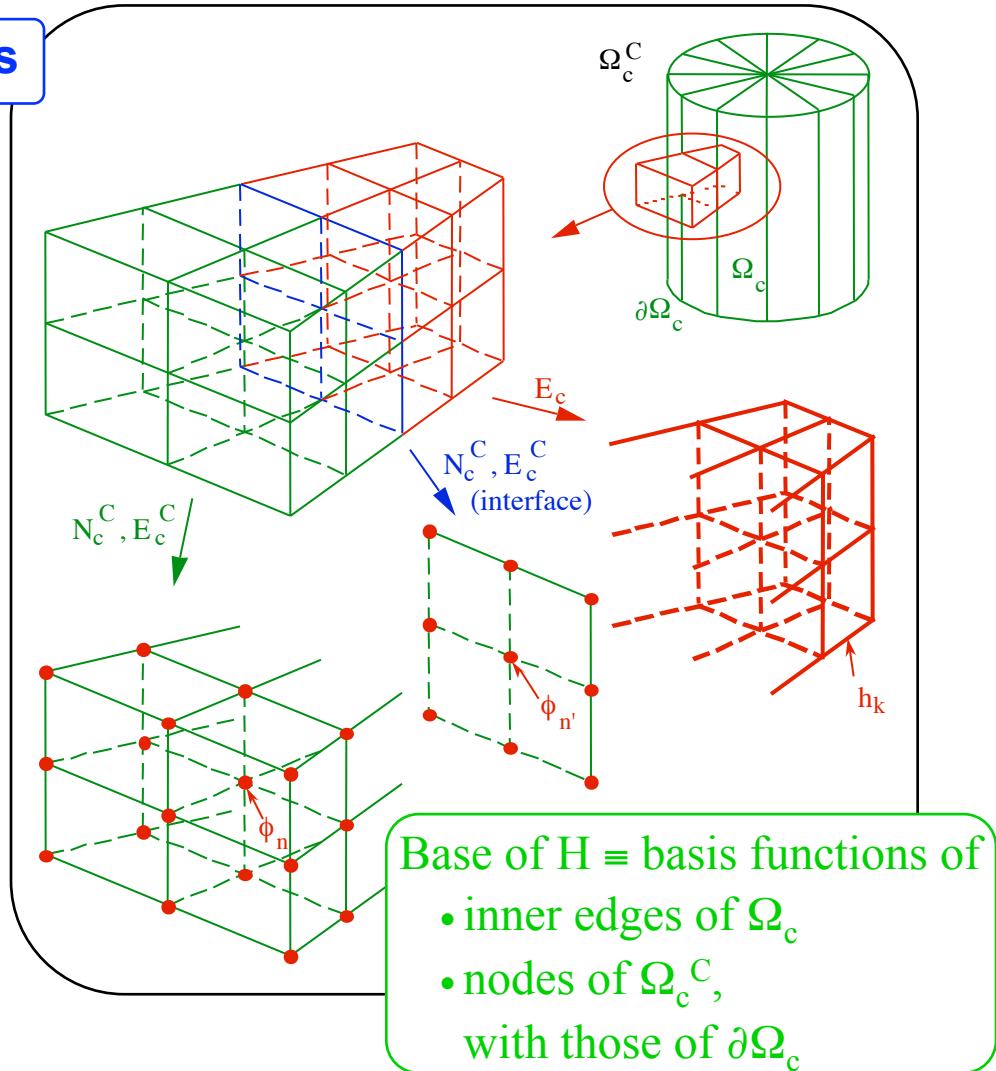
$$\mathbf{h} = \sum_{e \in E} h_a \mathbf{s}_a = \sum_{k \in E_c} h_k \mathbf{s}_k + \sum_{l \in E_c^C} h_l \mathbf{s}_l$$

$$h_l = \int_{l_{ab}} \mathbf{h} \cdot d\mathbf{l} = \int_{l_{ab}} -\text{grad } \phi \cdot d\mathbf{l} = \phi_{a_1} - \phi_{b_1}$$

$$\mathbf{h} = \sum_{k \in E_c} h_k \mathbf{s}_k + \sum_{l \in E_c^C} (\phi_{a_1} - \phi_{b_1}) \mathbf{s}_l$$

$$\mathbf{h} = \sum_{k \in E_c} h_k \mathbf{s}_k + \sum_{n \in N_c^C} \phi_n \mathbf{v}_n$$

with $\mathbf{v}_n = \sum_{nj \in E_c^C} \mathbf{s}_{nj}$



Kernel of the curl operator

Case of multiply connected domains

$$H = \{ \mathbf{h} \in S^1(\Omega); \text{curl } \mathbf{h} = 0 \text{ in } \Omega_c^C \}$$

$$\phi = \phi^{\text{cont}} + \phi^{\text{disc}}$$

$$\mathbf{h} = -\text{grad } \phi \text{ in } \Omega_c^C \text{ (cuts)}$$

$$\phi^+ - \phi^- = \phi|_{\Gamma^+_{eci}} - \phi|_{\Gamma^-_{eci}} = I_i$$

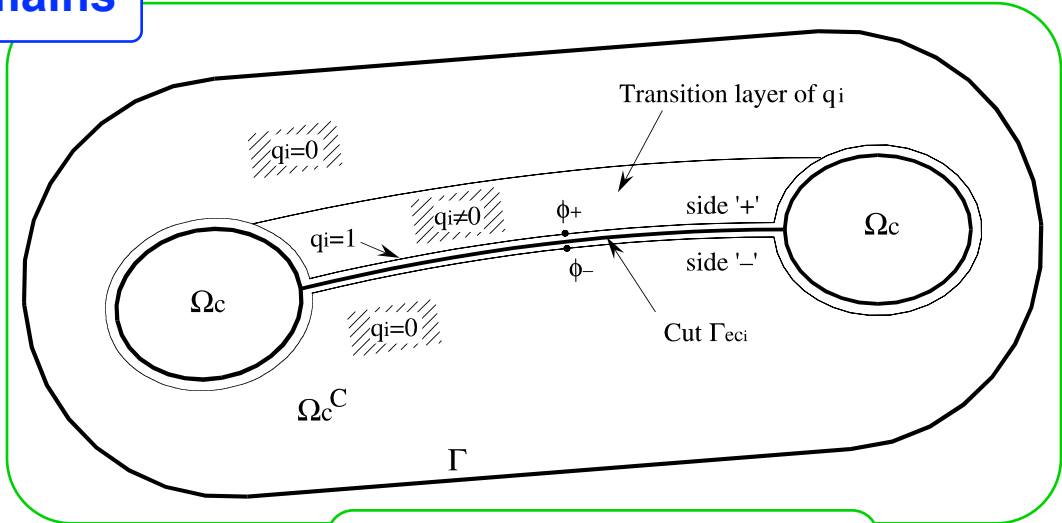
$$\phi^{\text{disc}} = \sum_{i \in C} I_i q_i$$

discontinuity of ϕ^{disc}

$$\mathbf{h} = \sum_{k \in A_c} h_k \mathbf{s}_k + \sum_{n \in N_c^C} \phi^{\text{cont}}_n \mathbf{v}_n + \sum_{i \in C} I_i \mathbf{c}_i$$

with $\mathbf{c}_i = \sum_{n_j} \mathbf{s}_{n_j}$

edges of Ω_c^C ← $n_j \in A_c^C$
 starting from a node of the cut ← $n \in N_{eci}$
 and located on side '+' ← $j \in N_c^{C+}$
 but not on the cut ← $j \notin N_{eci}$



- q_i • defined in Ω_c^C
- unit discontinuity across Γ_{eci}
- continuous in a transition layer
- zero out of this layer

- Basis of H = basis functions of**
- inner edges of Ω_c
 - nodes of Ω_c^C
 - cuts of C

Gauged subspace of S^1

Gauged space in Ω

$$\mathbf{b} = \text{curl } \mathbf{a} \quad \text{with} \quad \mathbf{a} = \sum_{e \in E} a_e \mathbf{s}_e \in S^1(\Omega) \quad , \quad \mathbf{b} = \sum_{f \in F} b_f \mathbf{s}_f \in S^2(\Omega)$$

$$\searrow \quad b_f = \sum_{e \in E} i(e, f) a_e \quad , \quad f \in F \quad \rightarrow \quad \text{matrix form:} \quad \boxed{b_f} = \boxed{C_{FE}} \quad \boxed{a_e}$$

Face-edge
incidence matrix

Tree \equiv set of edges connecting
(in Ω) all the nodes of Ω without
forming any loop (\hat{E})

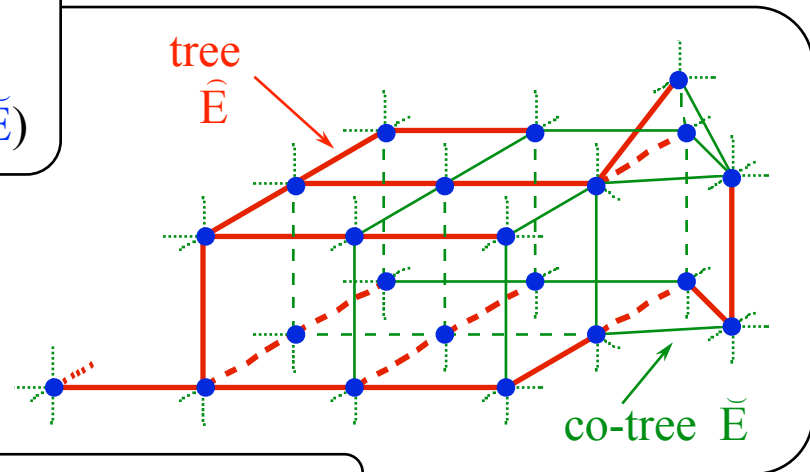
Co-tree \equiv complementary set of the tree (\check{E})

Gauged space of $S^1(\Omega)$

$$\check{S}^1(\Omega) = \{ \mathbf{a} \in S^1(\Omega) ; a_j = 0, \forall j \in \hat{E} \}$$

$$\mathbf{a} = \sum_{i \in \check{E}} a_i \mathbf{s}_i \in \check{S}^1(\Omega)$$

Basis of $\check{S}^1(\Omega) \equiv$ co-tree edge basis functions
(explicit gauge definition)



Mesh of electromagnetic devices

- ❖ **Electromagnetic fields extend to infinity (unbounded domain)**
 - ◆ **Approximate boundary conditions:**
 - zero fields at finite distance
 - ◆ **Rigorous boundary conditions:**
 - "infinite" finite elements (geometrical transformations)
 - boundary elements (FEM-BEM coupling)

- ❖ **Electromagnetic fields are confined (bounded domain)**
 - ◆ **Rigorous boundary conditions**

Mesh of electromagnetic devices

- ❖ **Electromagnetic fields enter the materials up to a distance depending of physical characteristics and constraints**

- ◆ Skin depth δ ($\delta \ll$ if $\omega, \sigma, \mu \gg$)

$$\delta = \sqrt{\frac{2}{\omega \sigma \mu}}$$

- ◆ mesh fine enough near surfaces (material boundaries)
- ◆ use of surface elements when $\delta \rightarrow 0$

Mesh of electromagnetic devices

❖ Types of elements

- ◆ 2D : triangles, quadrangles
- ◆ 3D : tetrahedra, hexahedra, prisms, pyramids
- ◆ Coupling of volume and surface elements
 - boundary conditions
 - thin plates
 - interfaces between regions
 - cuts (for making domains simply connected)
- ◆ Special elements (air gaps between moving pieces, ...)